TOSHIBA THS118

TOSHIBA HALL SENSOR GaAs ION IMPLANTED PLANAR TYPE

THS118

HIGH STABILITY MOTOR CONTROL. DIGITAL TACHOMETER. CRANK SHAFT POSITION SENSOR.

- Super Small Package.
- Excellent Temperature Characteristics.
- Wide Operating Temperature Range. (; −55~125°C)
- Excellent Output Voltage Linearity.

MAXIMUM RATINGS (Ta = 25°C)

CHARACTERISTIC		SYMBOL	RATING	UNIT	
Control Current	DC	Т	10**	mA	
	1s	$^{ m I_C}$	15**		
Power Dissipation	$P_{\mathbf{D}}$	100**	mW		
Operating Temperature Range		$T_{ m opr}$	-55~125	$^{\circ}\mathrm{C}$	
Storage Temperature Range		$ m T_{stg}$	-55~150	°C	

** Mounted on a printed circuit board.

MARKING



Unit in mm $^{+\,0.15}_{1.7\,-0.10}$ 0.5 0.5 0.05±0.05 +0 1(+) - 3(-) (INPUT) 2(+) - 4(-) (OUTPUT) **JEDEC EIAJ** TOSHIBA 10-2A1A

Weight: 0.0047g

ELECTRICAL CHARACTERISTICS (Ta = 25°C)

CHARACTER	ISTIC	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Internal Resistance (Input)		R_d	$I_{\text{C}} = 5 \text{mA}$	450	_	900	Ω
Residual Voltage Ratio		$v_{ m HO}/v_{ m H}$	$I_{C} = 5 \text{mA}, B = 0 / B = 0.1 \text{T}$	l	_	±10	%
Hall Voltage	(Note 1)	$ m v_H$	$I_{C} = 5mA, B = 0.1T$	55	_	140	mV
Temperature Coef	ficient (Note 2)	$ m v_{HT}$	I _C =5mA, B=0.1T T1=25°C, Ta=125°C	1	_	-0.06	%/°C
Linearity	(Note 3)	⊿K _H	$I_C = 5mA$, $B1 = 0.1T$, $B2 = 0.5T$	_	_	2	%
Specific Sensitivit	y (Note 4)	K*	$I_{C} = 5 \text{mA}, B = 0.1 \text{T}$		27	_	$\times 10^{-2} / \mathrm{T}$
Internal Resistance (Output) ROU		$R_{ m OUT}$	$I_C = 5mA$	580	_	1350	Ω

Note 1 : $V_H = V_{HM} - V_{HO} (V_{HM})$ is meter indication)

 $\mbox{Note 2} \ : \ \ V_{HT} = \frac{1}{V_{H(T1)}} \, \cdot \, \frac{V_{H(T2)} - V_{H(T1)}}{T2 - T1} \, \times \, 100 \, (\% \, / \, ^{\circ} C) \qquad \qquad V_{HO} \, : \ \ \mbox{Residual Voltage}$

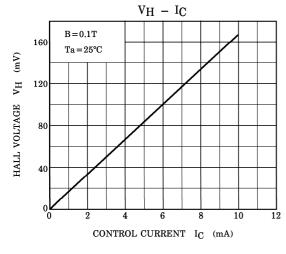
Note 3 : $\Delta K_{\text{H}} = \frac{K_{\text{H}(B2)} - K_{\text{H}(B1)}}{1/2 \{K_{\text{H}(B1)} + K_{\text{H}(B2)}\}} \times 100(\%), K_{\text{H}} = \frac{V_{\text{H}}}{I_{\text{C}} \cdot B}$ KH: Product Sensitivity

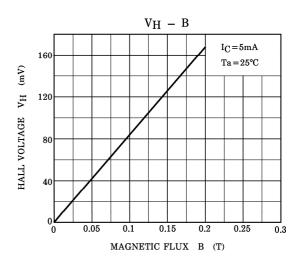
Note 4 : $K^*=V_H/(R_d\times I_C\times B)=K_H/R_d$

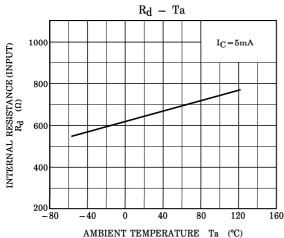
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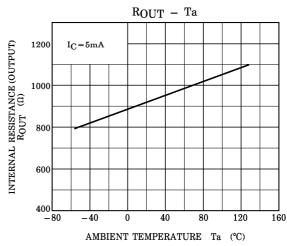
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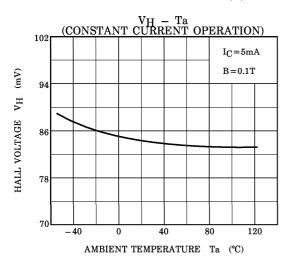
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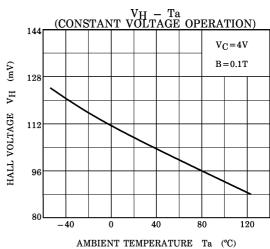












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